

IN THE SPECIFICATION

Please replace the paragraph beginning at page 5, line 8, with the following paragraph:

Motor 370 imparts a rotary motion to a shaft 374. Thus, motor 370 is a motion generating unit presenting a first rotary force at a first output locus embodied in shaft 374. Shaft 374 is coupled with a screw structure 376. Alternatively, shaft 374 may be integrally formed with screw structure 376. A screw follower unit 378 engages screw structure 376. Screw follower unit 378 responds to rotation of screw structure 376 in a first direction by moving toward rotary drive unit 72. Screw follower unit 378 responds to rotation of screw structure 376 in a second direction opposite to the first direction first direction by moving away from rotary drive unit 72. Thus, screw follower unit 378 is a motion translating unit coupled with the first output locus (shaft 374) for receiving the rotary force presented by motor 370. The motion translating unit embodied in screw follower unit 378 translates the rotary force and motion received from shaft 374 to present a linear force and motion related to the rotary force received from shaft 374 at connection structure 76. Connection structure 76 is connected with screw follower unit 378 and led over roller unit 77. Roller unit 77 is freely rotating on an axle 79. Axle 79 has been omitted from other drawings herein in order to reduce clutter and to simplify those other drawings. When screw follower unit 378 responds to rotation of screw structure 376 in the first direction by moving toward rotary drive unit 72, connection structure 76 is pulled upward and over roller unit 77, thereby lifting a battery (not shown in FIGs. 4 & 5). **When screw follower unit 378 responds to rotation of screw structure 376 in the second direction opposite to the first direction first direction by moving away from rotary drive unit 72, connection structure 76 is drawn downward over roller unit 77, thereby lowering a battery (not shown in FIGs. 4 & 5). Shaft 374 may extend through motor 370 for presenting a hand crank device 371. Moving hand crank device 371 to impart a rotary motion to shaft 374 effects a manually operated force generated to operate hoist 70.**

Please replace the paragraph beginning at page 7, line 21, with the following paragraph:

A support structure 250 includes a receiver section 252. Motion translation unit 274 is slidingly or telescopically received within receiver section 252 to permit motion translation unit 274 to move back and forth in sliding motion generally as indicated by a double-ended arrow 271. **Movement of translation unit 274 in directions indicated by arrow 271 may be effected manually, by way of example and not by way of limitation, applying a manual force in directions generally parallel with arrow 271 to a manually operated force generating unit such as a handle 302 attached with rotary drive unit 272. Alternatively, movement of translation unit 274 in directions indicated by arrow 271 may be effected using a hydraulic ram device such as, by way of example and not by way of limitation, a hydraulic ram device 304. Hydraulic ram device includes a hydraulic drive unit 306 affixed with receiver section 252. Hydraulic drive unit 306 hydraulically controls extension of a drive structure 310 with respect to drive unit 306. Drive structure 310 is coupled with a stop structure 308. Drive structure 310 responds to drive unit 306 and cooperates with stop structure 308 to move translation unit 274 in directions indicated by arrow 271.**